

# M-Bus Rev. 4.8

## M-Bus Rev. 4.8 communication protocol

[Supported device types and versions](#)  
[Communication line configuration](#)  
[Communication station configuration](#)  
[I/O tag configuration](#)  
[Specific data of Multical III device](#)  
[Parameters settings and data acquisition methods](#)  
[Literature](#)  
[Changes and modifications](#)  
[Document revisions](#)

### Supported device types and versions

Communication allows data reading from devices that support the M-Bus protocol by the Rev. 4.8 specification. Communication was tested against MULTICAL® III, MULTICAL® 5 measuring devices by KARMSTRUP Company, CALSTREEM EEM-C measuring device by Danfoss Company and PolluTherm Pt500 by Sensus. The communication was also verified against the water flow meter Sensus MeiStream 150 with communication module HRI-Mei using [EthMbus-5](#) converter manufactured by JC-e (it was necessary to configure a converter to TCP mode and use a [TCP/IP-TCP](#) line category).

### Communication line configuration

- Communication line category: [Serial](#), [SerialOverUDP Device Redundant](#), [MOXA IP Serial Library](#), [TCP/IP-TCP](#).  
**Note:** when using a [TCP/IP-TCP](#) line, in case of redundant systems multiple names/addresses separated by commas can be entered.
- Standard settings for most of M-Bus devices:
  - Mode 1: Baud rate 300, 8 bit, 1 stop bit, even parity, RTS=1, DTR=1.
  - Mode 2: Baud rate 2400, 8 bit, 1 stop bit, even parity, RTS=1, DTR=1.

### Line protocol parameters

The following station protocol parameters can be defined:

Keyword	Full name	Meaning	Unit	Default value
CHBR	Change Baudrate	Value Yes means that communication will be switched between modes 1 and 2 (only <a href="#">Serial</a> line). Value No means that communication will be performed using the mode 1 (300 Bauds).	-	No
SNKEBR	Send SND_NKE as Broadcast	The Yes value means that the SND_NKE (slave device initialization) command is sent as Broadcast before reading from the first station on the line. The No value means that the SND_NKE command is sent to each device individually before the start of the reading. Note: if the parameter is set to Yes, after sending Broadcast, there is a delay configurable by parameter <a href="#">WAI</a> .	-	Yes

### Communication station configuration

- Communication protocol: **M-Bus Rev 4.8**
- Station address is a decimal number within the range of 1..250 – slave address, it is derived from the serial number of the measurement device (last three digits). If last three digits are greater than 250, the highest digit is not to be taken into account. If the serial number is one of the numbers of 000, 300, 400, 500, 600, 700, 800, 900 then must be changed.

### Station protocol parameters

The following station protocol parameters can be defined:

Keyword	Full name	Meaning	Unit	Default value
ASCM	Address Scan Mode	Each reading of values increments the station address. This mode can be used to find a device with an unknown address.	-	No
RC	Retry Count	Poll repetition count in case of a communication error.	-	2
RT	Retry Timeout	Delay between poll repetition in case of a communication error.	ms	100 ms
WFT	Wait First Timeout	First waiting for response after sending the poll.	ms	800 ms
WT	Wait Timeout	Delay after transmitting the poll before reading the response.	ms	500 ms
MWR	Max Wait Retry	Repetition count of response readings till its finalization.	-	40

WAI	Wait After SND_NKE Broadcast	Delay after sending a broadcast SND_NKE, before reading from the first station on a communication line.	ms	8000 ms
WBR	Wait before REQ_UD2 Request	Delay before sending the REQ_UD2 poll request to a slave.	ms	4000 ms
SFAI	Set FCB Bit after SND_NKE	Parameter specifies whether an FCB bit in a poll request after sending SND_NKE should be set to 1 (YES) or 0 (NO).	-	YES
AFOR	Accept Following Records (0=disable,255=read all)	If the slave station has Variable Data available, the parameter specifies the number of records read during one polling of the station. A value of 255 means that all available records will be read.	-	0
RESB	Send Application Reset before REQ_UD2	Optional sending of "application reset" message (50h) prior to reading the values from the station.	-	NO
WUL	WakeUp Length	Length (given in characters) of so-called wake-up message sent before each poll. Value 0 disables sending of wake-up message.	bytes	0
WUD	WakeUp Delay	Delay between wake-up message and poll.	ms	400
FULL_DEBUG	Full Debug	Enables debug logs on the communication and acquired data.	-	NO
MULTICALIII	Multical III	Enables decoding the <a href="#">Manufacture specific data</a> of Multical III device.	-	NO

String containing the protocol parameters is being defined as follows:

```
Keyword=value;Keyword=value; ...
```

Example:

```
RC=1;RT=500;LBR=1;
```

If there is used a keyword with an invalid value in the initialization string, there will be used corresponding default value according the table 1.

## I/O tag configuration

Possible I/O tag types: **Ai, Ci, TiA, TiR, TxtI**

Two types of addresses can be configured:

- **Simple address:** a number that is an index of value in M-Bus data packet. To get detailed information on unknown device activate debug logs using the parameter **FULL\_DEBUG**.  
An example of debug log (individual rows correspond with addresses 1 to 9, value is displayed at the end of listing after the text "Val"):

```
>> Adr.1,DF:0CH (8 digit BCD)(inst. val),VIF:05H=Energy 0*10^2 [Wh],VIFE:7DH=Multiplicative corr. factor 10^3,Val:0
>> Adr.2,DF:0CH (8 digit BCD)(inst. val),VIF:15H=Volume 0*10^-1 [m3],Val:0
>> Adr.3,DF:0CH (8 digit BCD)(inst. val),VIF:3DH=Volume Flow 0*10^-1 [m3/h],Val:0
>> Adr.4,DF:0CH (8 digit BCD)(inst. val),VIF:2DH=Power 0*10^2 [W],Val:0
>> Adr.5,DF:02H (16 bit int)(val during err),VIF:5AH=Flow temperature 0*10^-1 [C],Val:0
>> Adr.6,DF:02H (16 bit int)(val during err),VIF:5EH=Return temperature 0*10^-1 [C],Val:0
>> Adr.7,DF:03H (24 bit int)(val during err),VIF:60H=Temperature difference 0*10^-3 [K],Val:0
>> Adr.8,DF:0CH (8 digit BCD)(inst. val),VIF:78H=Fabrication No.,Val:53155203
>> Adr.9,DF:0CH (8 digit BCD)(inst. val),VIF:7DH=Extension of VIF-codes,VIFE:10H=Customer location,Val:53155203
```

- **Address of header objects:** in format *0.subadr* enables to address objects located in a header of an answer. A device can answer using a fixed or variable respond that have different header contents. Following table lists header objects and their addresses for fix and variable respond.

Object	Value type	Address in fix respond	Address in variable respond
Identification No.	Ci, TxtI	0.0	0.0
Manufacturer	TxtI (3 characters)	-	0.1
Version	Ci	-	0.2
Medium	Ci	-	0.3
Access No.	Ci	0.1	0.4
Status	Ci	0.2	0.5
Signature	Ci	-	0.6

An example of debug log for variable respond:

```
Variable data respond CI=0x72 mode 1 from St:'B.MBUS_SENSUS'(0) detected.
>> Adr.0.0,Identification No.,Val=53155203
>> Adr.0.1,Manufacturer,Val='SEN'
>> Adr.0.2,Version,Val=12
>> Adr.0.3,Medium,Val=4
>> Adr.0.4,Access Nr.,Val=50
>> Adr.0.5,Status,Val=16
>> Adr.0.6,Signature,Val=0
```

## Specific data of Multical III device

Multical III device sends extended "manufacture specific data". Activating the parameter **MULTICALIII** allows to configure I/O tags according to the following table:

Address	Value description	Type
12	Access counter	Ci
13	Number of customer 1	Ci
14	Number of customer 2	Ci
15	Info	Ci
16	TAR2	Ci
17	TL2	Ci
18	TAR3	Ci
19	TL3	Ci
20	AUX1	Ai
21	AUX2	Ai
22	Prog_No	Ci
23	Config	Ci
24	Date	TiA
25	Date*	TiA

## Parameters settings and data acquisition method

Recommended [polling parameters](#) are at least 1 minute. When the polling time comes, the before polling the first station on the line a SND\_NKE(255) datagram is broadcasted, i.e. init for all measuring devices (Slaves) and KOM process waits for a period specified by the parameter [WAI](#). The slaves prepare all current measured values and implicitly change their Baudrate to 300.

Then the communication speed can be optionally changed to higher speed (specified on communication line as mode 2) by SND\_UD data, if it configured by the means of the line parameter [Change Baudrate](#). Only baudrates 300/600/1200/2400/9600/19200/3840 are supported by M-Bus protocol.

Note: change of baudrate is supported only on a [Serial](#) line.

Then a REQ\_UD2 poll request is sent to every slave, after waiting according to value specified by the parameter [WBR](#)) to which they all should respond by the data datagram RSP\_UD.

Times of individual values are not set to the time when the telegram was received, but to the time of required [polling period](#). So if the period is set to 1 hour, all the times of values are set to given hour.

**Note:** Polling period as well as station parameters should be the same on all stations and one line.

## Literature

- [The M-Bus: A Documentation Rev. 4.8](#)

## Changes and modifications

- November 22nd, 2005 - Redesignated by M-Bus Rev. 4.8.

## Document revisions

- Ver. 1.0 - June 26th, 2000 – document creation.
- Ver. 1.1 – November 9th, 2000 – testing Danfoss CALSTREEM.
- Ver. 1.2 – December 14th, 2000 – Change of the outputs AUX1 and AUX2 from Ci to Ai
- Ver. 1.3 - November 22nd, 2005 - Redesignated by M-Bus Rev. 4.8.



### Related pages:

[Communication protocols](#)